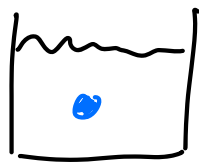


Recap so far



colloidal particle in a fluid (i)

① Equation of motion

Generalized Langevin eq^o: $m\dot{x} = p$; $\dot{p} = -V'(x) - \int_0^t ds K(t-s)\dot{x}(s) + \xi(t)$

where $K(t)$ is a Gaussian noise with $\langle \xi(t) \xi(t') \rangle = k_B T K(t-t')$

White noise limit when fluid relaxation time \ll colloid

$m\dot{x} = p$; $\dot{p} = -V'(x) - \gamma\dot{x} + \xi(t)$, where $\xi(t)$ is a Gaussian

White noise with $\langle \xi(t) \rangle = 0$ & $\langle \xi(t) \xi(t') \rangle = 2\gamma k_B T \delta(t-t')$

Overdamped limit In viscous fluid, inertia is negligible &

$\dot{x} = -\mu V'(x) + \eta(t)$, with $\mu = \frac{1}{\gamma}$ the particle mobility

& $\langle \eta(t) \eta(t') \rangle = 2\mu k_B T \delta(t-t')$

② Path probability $P[\eta(t)] \propto \frac{1}{Z} e^{-\int dt \eta(t)^2}$

For an α discretization $x(t+\Delta t) - x(t) = F(x(t)) + \int_t^{t+\Delta t} ds \eta(s)$

$$P[\{x(t)\}] \propto \frac{1}{Z} e^{-\int dt \left\{ \frac{[\dot{x} - F(x)]^2}{4k_B T} + \alpha F'(x) \right\}}$$

③ Probability distribution of $x(t)$

$$\partial_t P(x, t | x_0, 0) = \frac{\partial}{\partial x} \left[-F(x) + k_B T \frac{\partial}{\partial x} \right] P(x, t | x_0, 0)$$

When $F(x) = -V'(x)$, $P(x) = \frac{1}{Z} e^{-\beta V(x)}$ is a time independent solution of the Fokker-Planck equation. (17)

Comment: For $P(x)$ to be normalizable, we need $\int dx e^{-\beta V(x)} < +\infty$
 $\Rightarrow V(x)$ has to diverge fast enough.

If $V(x) \sim \varepsilon \log|x|$, $e^{-\beta V(x)} \sim \frac{1}{|x|^{\beta\varepsilon}}$ not integrable for $\varepsilon\beta \leq 1$
 $\Rightarrow kT \geq \varepsilon$

\Rightarrow at high temperature, the system does not equilibrate.

The potentials that diverge faster than logarithmically are called confining potentials.

Today: (i) N dimensional Fokker-Planck eq^o

(ii) Spectral theory of the Fokker-Planck eq^o

(iii) Study time-reversal symmetry in the steady state

2) The N-dimensional Fokker-Planck equation

(3)

Let's consider $x_i = F_i(x_1, \dots, x_n) + z_i$ where z_i are Gaussian s.t. $\langle z_i \rangle = 0$

$$\text{and } \langle z_i(t) z_k(s) \rangle = B_{ik} \delta(t-s)$$

$$P(x_1, \dots, x_n; t) = \langle \bar{z} \delta(x_i - g_i(t)) \rangle_{\bar{z}}$$

↑ *numbers*
↑ *stochastic processes*

$$\begin{aligned} \frac{\partial P}{\partial t} &= \sum_h \left\langle \frac{\partial}{\partial g_h} \left[\bar{z} \delta(x_i - g_i) \right] \dot{g}_h \right\rangle_{\bar{z}} + \sum_{j,h} \left\langle \frac{B_{jh}}{2} \frac{\partial^2}{\partial g_j \partial g_h} \bar{z} \delta(x_i - g_i) \right\rangle_{\bar{z}} \\ &\quad \text{Ito } \left\langle \frac{\partial}{\partial g_h} \left[\bar{z} \delta(x_i - g_i) \right] F_h \right\rangle_{\bar{z}} \\ &= \int \bar{z} dg_i \left\{ \sum_h \frac{\partial}{\partial g_h} \left[\bar{z} \delta(x_i - g_i) \right] F_h P + \sum_{j,h} \frac{\partial^2}{\partial g_j \partial g_h} \left[\bar{z} \delta(x_i - g_i) \right] \frac{B_{jh}}{2} P \right\} \end{aligned}$$

$$\stackrel{\text{IBP}}{=} \int \bar{z} dg_i \cdot \left[\bar{z} \delta(x_i - g_i) \right] \left\{ \sum_h - \frac{\partial}{\partial g_h} [F_h P] + \sum_{j,h} \frac{\partial^2}{\partial g_j \partial g_h} \left[\frac{B_{jh}}{2} P \right] \right\}$$

leading to the Fokker-Planck equation

$$\frac{\partial P(x_1, \dots, x_n, t)}{\partial t} = \sum_h \frac{\partial}{\partial x_h} \left[-F_h - \sum_j \frac{\partial}{\partial x_j} \frac{B_{jh}}{2} \right] P(x_1, \dots, x_n, t)$$

Conservation of probability:

This can again be written as

$$\frac{\partial P}{\partial t} = - \sum_h \frac{\partial}{\partial x_h} J_h = - \vec{\nabla} \cdot \vec{J}, \text{ where the probability}$$

current is given by

$$J_h = \underbrace{F_h P}_{\text{advection}} - \underbrace{\sum_j \frac{\partial}{\partial x_j} \frac{B_{jh}}{2} P}_{\text{diffusion}}$$

Bjℏ tells us how noise along \hat{q} leads to a diffusive current along \hat{p} .

(4)

Application: Undamped Langevin equation & the Kramers equation

$$m\dot{q} = p; \dot{p} = -\gamma \frac{p}{m} - V'(q) + \sqrt{2\gamma\hbar T} \zeta(t) \quad \text{with } \langle \zeta(t) \rangle = 0 \quad (m=1)$$

and $\langle \zeta(t) \zeta(s) \rangle = \delta(t-s)$. As before, we can understand this equation as experiencing noise on both q & p , but with $B_{qq} = B_{qp} = B_{pq} = 0$ & $B_{pp} = 2\gamma\hbar T$. Thus the equation for $P(q, p, t)$ reads

$$\partial_t P(\vec{q}, \vec{p}, t) = -\frac{\partial}{\partial q} \left(\frac{p}{m} P \right) + \frac{\partial}{\partial p} \left(\gamma p + V'(q) \right) P + \gamma\hbar T \frac{\partial^2}{\partial p^2} P$$

This is called the Kramers equation.

Steady state solution in the presence of a confining potential

$$H = \frac{p^2}{2m} + V(q) \Rightarrow \partial_q (e^{-\beta H}) = -\beta V'(q) e^{-\beta H} \quad \& \quad \partial_p e^{-\beta H} = -\beta \frac{p}{m} e^{-\beta H}.$$

Let's show that the steady-state solution is $e^{-\beta H}$.

$$\begin{aligned} & -\frac{\partial}{\partial q} \left(\frac{p}{m} e^{-\beta H} \right) + \frac{\partial}{\partial p} \left(\cancel{\gamma p e^{-\beta H}} + V'(q) e^{-\beta H} + \gamma\hbar T \left(\cancel{-\beta \frac{p}{m} e^{-\beta H}} \right) \right) \\ & = -\frac{p}{m} \left[-\beta V'(q) e^{-\beta H} \right] + V'(q) \left[-\beta \frac{p}{m} e^{-\beta H} \right] = 0 \end{aligned}$$

Again, the steady state corresponds to the Boltzmann weight.

Comment: The steady state is independent from γ , which is a purely kinetic parameter and plays no role in the thermodynamics of equilibrium systems. It, however, controls the relaxation rate of the system towards steady-state.

Comment: The same result holds for a space-dependent viscosity $\gamma(\vec{q})$, but not for $T(\vec{q})$, which leads to a nonequilibrium steady state.

Recap so far:

Stochastic dynamics: $\dot{\vec{\pi}} = -\mu \vec{\nabla} V + \sqrt{2\mu kT} \vec{\xi}$

→ clear physical picture of the dynamics

→ simulations

→ stochastic calculus → evolution of observable,
→ correlation functions

Fokker-Planck equation: $\partial_t P = -\vec{\nabla} \cdot [-\mu \vec{\nabla} V P - \mu kT \vec{\nabla} P]$

→ hard to simulate

→ statistical information/intuition through $P(\vec{\pi})$

e.g. Show that $P_s(\vec{\pi}) \propto e^{-\beta H}$

→ Now: very powerful operator calculus

3) The Fokker-Planck operator

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$$\partial_t P = \frac{\partial}{\partial x} \left[hT \frac{\partial}{\partial x} - F(x) \right] P(x,t) \quad (1) \Leftrightarrow \partial_t P = -H_{FP} P \quad \text{where}$$

$$H_{FP} = -\frac{\partial}{\partial x} \left[hT \frac{\partial}{\partial x} - F(x) \right] \text{ which acts on the Hilbert space of functions}$$

$\mathcal{H}(P)$ that depends on the dimensions & boundary conditions of the problem.

3.1) Relaxation towards equilibrium

Q: How does a system relax towards equilibrium?

Tentative ansatz: $P(x,t) = e^{-\lambda t} P_0(x)$

$$(1) \quad \partial_t P = -H_{FP} P_0(x) e^{-\lambda t} = -\lambda P_0 e^{-\lambda t} \Leftrightarrow H_{FP} P_0(x) = \lambda P_0(x)$$

$\rightarrow P_0(x)$ is an eigenfunction of H_{FP} & λ is the corresponding eigenvalue.

If H_{FP} is diagonalizable in $\mathcal{H}(P)$, then is a basis $\varphi_\alpha(x)$ of eigenfunctions of H_{FP} , with associated eigenvalues λ_α , such that $H_{FP} \varphi_\alpha(x) = \lambda_\alpha \varphi_\alpha(x)$

Evolution of P

Since φ_α is a basis, any $P(x,t)$ can be written as $P(x,t) = \sum_\alpha C_\alpha(t) \varphi_\alpha(x)$

$$\begin{aligned} \text{then } \partial_t P &= -H_{FP} \sum_\alpha C_\alpha(t) \varphi_\alpha(x) = -\sum_\alpha C_\alpha(t) H_{FP} \varphi_\alpha(x) \\ &= -\sum_\alpha C_\alpha(t) \lambda_\alpha \varphi_\alpha(x) \end{aligned}$$

$$\text{but also } \partial_t P = \partial_t \sum_\alpha C_\alpha(t) \varphi_\alpha(x) = \sum_\alpha \dot{C}_\alpha(t) \varphi_\alpha(x)$$

Since φ_α is a basis, this implies $\dot{C}_\alpha(t) = -\lambda_\alpha C_\alpha(t)$ & $C_\alpha(t) = e^{-\lambda_\alpha t} C_\alpha(0)$

① Take $P_0(x)$

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② Expand it as $P_0(x) = \sum_{\alpha} C_{\alpha}(0) \varphi_{\alpha}(x)$

③ For all times t , $P(x,t) = \sum_{\alpha} C_{\alpha}(0) e^{-\lambda_{\alpha} t} \varphi_{\alpha}(x)$

If you can diagonalize $H_{FP} \Rightarrow$ problem solved!

Comment: $\text{Re}(\lambda_{\alpha}) > 0$ is required, otherwise $P(x,t)$ blows up as $t \rightarrow \infty$.

The existence of a steady state requires $\inf_{\alpha} \text{Re}(\lambda_{\alpha}) = \lambda_0 = 0$

Equilibrium dynamics with a confining potential $V(x)$

The Perron Frobenius theorem states that, for a confining potential,

① H_{FP} is diagonalizable with $\lambda_{\alpha} \in \mathbb{R}^+$

② There is a unique ground state such that $\lambda_0 = 0$.

As $t \rightarrow \infty$, the contribution of excited states decay exponentially

and the system equilibrates: $P(x,t) = \sum_{\alpha} C_{\alpha}^0 e^{-\lambda_{\alpha} t} \varphi_{\alpha}(x) \rightarrow C_0 P_0(x)$

Gapped spectrum and relaxation rate

Consider $P(x,0) = c_1 \varphi_1(x) + c_2 \varphi_2(x)$ with $\text{Re}(\lambda_1) < \text{Re}(\lambda_2)$, then

$$P(x,t) = c_1 \varphi_1 e^{-\lambda_1 t} + c_2 \varphi_2 e^{-\lambda_2 t} = c_1 e^{-\lambda_1 t} \left[\varphi_1 + \underbrace{\frac{c_2}{c_1} \varphi_2 e^{-(\lambda_2 - \lambda_1)t}}_{\rightarrow 0} \right]$$

φ_2 is forgotten at a typical rate which is $\frac{1}{\lambda_2 - \lambda_1}$. $\epsilon \gg 1/(\lambda_2 - \lambda_1)$

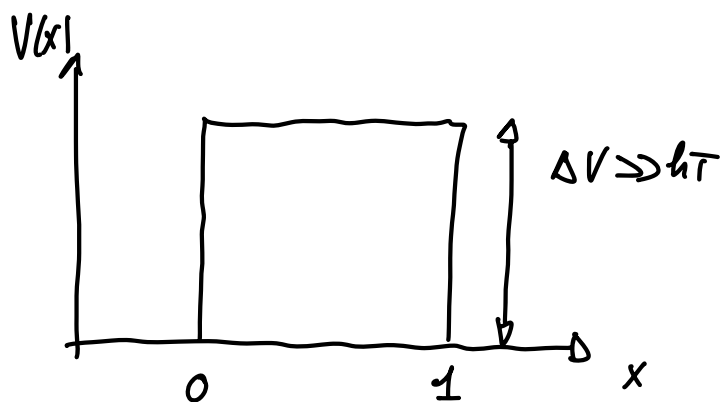
\Rightarrow the typical time scales of the system can be read in the spectrum of H_{FP} .

\Rightarrow can be used to define metastability and reaction paths.

[Touati - Nicolai, Kurchan, J. Stat. Phys. 116, 1201 (2004)]

⇒ For systems with N degrees of freedom, we may end up with a continuous spectrum as $N \rightarrow \infty$ ($\lambda_2 - \lambda_1 \rightarrow 0$). The relaxation can then become very slow as in glassy materials. $t \rightarrow \infty$ & $N \rightarrow \infty$ do not necessarily commute.

3.2) Example of diagonalization of H_{FP} : diffusion with absorbing boundaries



If the particle exits $[0,1]$, then it cannot come back.

⇒ model as a random walk in $[0,1]$ with absorbing boundary conditions.

Q: how much time until absorption?

This is the simplest form of a question frequently encountered:
how does a diffusive molecule reach a target? (Here, target $x=1$)

More generally:

Starting from x_0 in $(0,1)$, how does the probability to remain in $[0,1]$ evolve in time? ⇒ $P(x,t|x_0,0)$ conditioned to having stayed in $[0,1]$ ⇒ $P(x,t|x_0,0) = 0$ for $x \leq 0$ & $x \geq 1$.

In practice, solve $\frac{\partial}{\partial t} P(x,t) = \frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} P(x,t)$ with $P(x=0,t) = P(x=1,t) = 0$.

Survival probability: $Q(t) = \int_0^1 dx P(x,t)$ is the probability that the system is still in $[0,1]$ at time t .

Solution: Consider $H_{FP} = -D \frac{\partial^2}{\partial x^2}$ and look for a basis of eigenfunctions satisfying the boundary conditions:

$$H_{FP} \psi = \lambda \psi \Leftrightarrow \psi''(x) = -\frac{\lambda}{D} \psi(x)$$

$$\Rightarrow \psi(x) = A e^{i\sqrt{\frac{\lambda}{D}}x} + B e^{-i\sqrt{\frac{\lambda}{D}}x}$$

Boundary conditions $\psi(0) = 0 \Rightarrow A = -B$ & $\psi(x) = 2iA \sin(\sqrt{\frac{\lambda}{D}}x)$

$$\psi(1) = 0 \Rightarrow \sqrt{\frac{\lambda}{D}} = h\pi; h \in \mathbb{Z}^+$$

$$\Rightarrow \psi_h(x) = \sin(h\pi x) \text{ & } \lambda_h = D h^2 \pi^2 \quad (\text{Fourier basis})$$

$$t=0 \quad P(x,0) = \sum_{h=1}^{\infty} C_h \sin(h\pi x); \quad C_h = 2 \int_0^1 dx \sin(h\pi x) P(x,0)$$

$$\Rightarrow P(x,t) = \sum_{h=1}^{\infty} C_h \sin(h\pi x) e^{-D\pi^2 h^2 t}$$

Example: $P(x,0) = \delta(x-x_0) \Rightarrow C_h = 2 \sin(h\pi x_0)$

$$P(x,t) = \sum_{h=1}^{\infty} 2 \sin(h\pi x) \sin(h\pi x_0) e^{-D\pi^2 h^2 t}$$

$$\underset{t \rightarrow \infty}{\sim} 2 \sin(\pi x) \sin(\pi x_0) e^{-D\pi^2 t}$$

$$Q(t) \sim \frac{4}{\pi} \sin(\pi x_0) e^{-D\pi^2 t}$$

\Rightarrow late-time absorption rate $\kappa = \frac{1}{D\pi^2}$ with a position-dependent modulation of the survival probability.

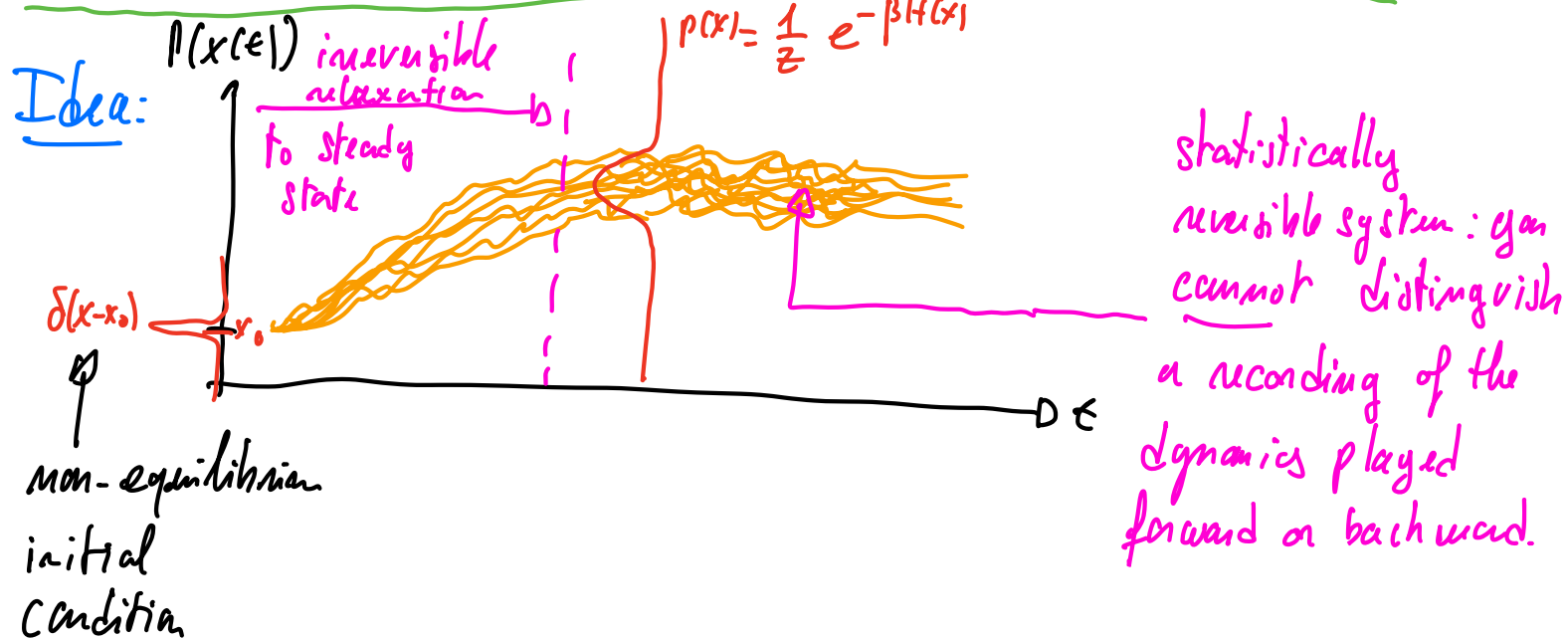
Chapter 4] Time Reversed Symmetry

(10)

Historically, equilibrium corresponds to $P(x) = \frac{1}{Z} e^{-\beta H(x)}$ (d. 333) (d. 044)

Modern perspective on statistical mechanics puts an emphasis on dynamics & characterize equilibrium by a statistical time reversal symmetry in the steady state.

Q: What does it mean & how do we characterize that?



1) Propagator & Dirac Bra-ket notation

Remember quantum mechanics: $P(x)$ lives in a Hilbert space, which is a vector space. We can denote the corresponding vector as $|P\rangle$.

Scalar product: $\langle f|g\rangle = \int dx f^*(x) g(x)$

Adjoint operator: $\langle f|H|g\rangle = \langle H^\dagger f|g\rangle$

E.g. $\langle f|\partial_x g\rangle = \int dx f^*(x) \partial_x g = - \int dx \partial_x f^* g = \langle -\partial_x f|g\rangle \Rightarrow \frac{\partial}{\partial x}^\dagger = -\frac{\partial}{\partial x}$

$= \langle \frac{\partial}{\partial x} f|g\rangle$

Position operator & representation

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$|x\rangle$ such that $\hat{x}|x\rangle = x|x\rangle$, $|x\rangle$ position basis

↳ position operator

Observable: $O(x)$ → operator \hat{O} such that $\hat{O}|x\rangle = O(x)|x\rangle$

e.g. $\hat{p}|x\rangle = p(x)|x\rangle$

Scalar product: $\langle x|$ such that $\langle x|x'\rangle = \delta(x-x')$

Flat measure: $1 \rightarrow \int dx |x\rangle$

Representation of probability distribution:

$$\hat{P} 1 \rightarrow \equiv |P\rangle = \hat{P} \int dx |x\rangle = \int dx \hat{P} |x\rangle = \int dx P(x) |x\rangle$$

component ↙ ↘ basis vector

Probabilities

$$\langle x|P\rangle = \int dx' P(x') \underbrace{\langle x|x'\rangle}_{\delta(x-x')} = P(x) \quad \text{different from QM.}$$

Average of observables:

$$\begin{aligned} \langle O(x) \rangle &= \int dx O(x) P(x) = \int dx \int dx' \delta(x-x') O(x') P(x') \\ &= \int dx \int dx' \langle x|x'\rangle O(x') P(x') \\ &= \langle - | O | P \rangle \end{aligned}$$

Fokker-Planck equation:

$$\partial_t |P(t)\rangle = \int dx \partial_t P(x,t) |x\rangle = - \int dx H_{FP} P(x,t) |x\rangle = - H_{FP} |P(t)\rangle$$

Formal solution:

$$|P(t)\rangle = e^{-tH_{FP}} |P_0\rangle$$

Initial condition $x=x_0$:

Any observable O such that $\langle O(t=0) \rangle = O(x_0) = \int dx \delta(x-x_0) O(x)$

$$\Rightarrow P(x, t=0) = \delta(x-x_0) \Rightarrow |P(t=0)\rangle = |x_0\rangle \Rightarrow$$

$$\Rightarrow |P(t)\rangle = e^{-tH_{FP}} |x_0\rangle$$

Note that $\int dx \delta(x-x_0) = 1$ so that P is normalized

Propagation:

The probability to go from x_0 to x in a time t is called a "propagator".

$$P(x, t | x_0, 0) = \langle x | e^{-tH_{FP}} | x_0 \rangle$$

measure the probability in x \uparrow evolve for a time t \uparrow start here

2 > Detailed balance & time-reversal symmetry

Statistical time reversibility: a succession of events is as likely to occur as the time reversed sequence.

E.g. $P(x, t; x_0, t_0) = P(x_0, t; x, t_0)$ for $t_0 < t$ (1)

Claim: At large times ($t_0 \rightarrow \infty$), the evolution induced by H_{FP} leads to a steady-state that is time-reversal symmetric.

Q: Can we read directly in H_{FP} this property?

(ie without having to solve for $P(x, t; x_0, t_0)$)

Since $P(a, b) = P(a|b) P(b)$, (1) can be rewritten as:

$$P(x, t | x_0, t_0) P(x_0, t_0) = P(x_0, t | x, t_0) P(x, t_0)$$

$$\Leftrightarrow \langle x | e^{-(t-t_0)H_{FP}} | x_0 \rangle P(x_0, t_0) = \langle x_0 | e^{-(t-t_0)H_{FP}} | x \rangle P(x, t_0) \quad (2)$$

If $t_0 \rightarrow \infty$, $P(x_0, t) \rightarrow P_S(x_0)$ the stationary state

$$\text{Since } \langle x_0 | e^{-(t-t_0)H_{FP}} | x \rangle \in \mathbb{R},$$

$$\langle x_0 | e^{-(t-t_0)H_{FP}} | x \rangle = \left[\langle x_0 | e^{-(t-t_0)H_{FP}} | x \rangle \right]^{\dagger} = \langle x | e^{-(t-t_0)H_{FP}^{\dagger}} | x_0 \rangle$$

$$\begin{aligned} (2) \Leftrightarrow \langle x | e^{-(t-t_0)H_{FP}} | x_0 \rangle &= P_S(x) \langle x | e^{-(t-t_0)H_{FP}^{\dagger}} | x_0 \rangle P_J^{-1}(x_0) \\ &= \langle x | P_S e^{-(t-t_0)H_{FP}^{\dagger}} P_J^{-1} | x_0 \rangle \end{aligned}$$

$$\text{Expand for small } t-t_0 : e^{-\mu H_{FP}} = \mathbb{I} - \mu H_{FP}$$

$$(*) \Leftrightarrow \langle x | x_0 \rangle - (t-t_0) \langle x | H_{FP} | x_0 \rangle = \langle x | x_0 \rangle - (t-t_0) \langle x | P_J H_{FP}^{\dagger} P_J^{-1} | x_0 \rangle$$

$$\text{Holds } \forall x, x_0, \text{ so that TRS} \Rightarrow \boxed{H_{FP} = P_J H_{FP}^{\dagger} P_J^{-1} \quad \text{or} \quad H_{FP}^{\dagger} = P_J^{-1} H_{FP} P_J} \quad (3)$$